# Wikiprint Book

**Title: General information** 

Subject: DEEP - Public/User\_Guide/SDV\_KNLs

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## **General information**

We have 3 KNLs in the SDV right now.

All KNLs nodes have their own local NVMe device installed.

### Node allocation

Nodes can be allocated through the Slurm based batch system that is also used for the DEEP-EST system and the SDV Xeon Cluster. You can start an interactive session on our KNLs like this:

srun --partition=knl -N 2 -n 8 --pty /bin/bash -i

When using a batch script, you have to adapt the --partition option within your script: --partition=knl

#### Available knl partitions

- knl: The DEEP-ER knl nodes (all of them, regardless of cpu and configuration)
- knl256: the 256-core knls (knl5)
- knl272: the 272-core knls (knl4,knl6)
- snc4: the knls configured in SNC-4 mode

## Compiling

Use the -xMIC-AVX512 flag instead of -mmic. Check actual vectorisation with -qopt-report=5 -qopt-report-phase=vec  $\rightarrow$  info given in \*.optrpt files

#### Multi-node Jobs

The KNL nodes are only connected via Gigabit Ethernet, hence there is no need to load the Extoll module to run jobs on multiple nodes.

### 5 things to consider when using KNL

- i. Make sure to use the fast MCDRAM:
  - When MCDRAM is in cache mode:
    - No changes are needed.
  - When MCDRAM is in flat mode:
    - If the total memory footprint of the application is smaller than the size of MCDRAM: numactl ?m 1 ./my\_application.out (Allocations that don?t fit into MCDRAM make the application fail.)
    - If the total memory footprint of the application is larger than the size of MCDRAM: numactl ?p 1 ./my\_application.out (Allocations that don?t fit into MCDRAM spill over to DDR)
  - To make a manual choice of what should be allocated in the MCDRAM: Use the memkind library.
- i. Verify that the pinning is as you wish:
  - Start job on KNL node(s).
  - Log in on KNL.
  - Invoke htop.
  - Check the load distribution.
  - Remark: Each core can execute 1, 2 or 4 threads. On KNL ? unlike on KNC ? already one thread per core can lead to optimal performance.
- i. Use VTune/Advisor to analyse the performance:
  - Start job on KNL node(s).
  - Log in on KNL.
  - 'module load VTune / Advisor'.
  - Run amplxe-gui / advixe-gui.
  - Follow instructions.
  - Remark: If you run into erros of the sort ?sepdk not available? please contact the administrator. Both tools rely on a kernel module to access hardware counter.

- i. Provide hints to the compiler:
  - Check \*optrpt for info on vectorisation.
  - If you find ?unaligned...? → add alignment in your code by adding "#pragma vector aligned" before the loop.
  - If a loop does not vectorise although it clearly should, you can add "#pragma simd" before the loop.
  - Re-check \*.optrpt.
  - Re-check in VTune / Advisor
- i. Verify the performance via benchmarks:
  - Set up JUBE for your code.
  - Benchmark the various versions with proper timing.
  - Be aware: VTune / Advisor sometimes give estimates that are a little off. It's imperative to check the actual performance.